G205 Fundamentals of Computer Engineering

CLASSES 18, Wed. Nov. 10 2004

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M-W, 1:30pm-3:10pm

All-Pairs Shortest Paths

- Finding shortest path between all pairs of vertices in a graph
- Input:
  - G=(V,E)
  - $w: E \to \mathbf{R}$
- Output: For each pair of vertices u and v in V we want the least weight path from u to v

Representation of Input

- For APSP graph represents by an adjacency matrix $W = (w_{ij})$
  - $w_{ij} = 0$ if $i = j$
  - $w_{ij} = w(i,j)$ if $i \neq j$ and $(i,j) \in E$
  - $w_{ij} = \infty$ if $i \neq j$ and $(i,j) \notin E$
- Negative-weight edges → OK
- Negative-weight cycles → not OK

Representation of Output

- n x n matrix $D = (d_{ij})$
  - d_{ij} = shortest path weight from i to j
  - At termination: $d_{ij} = \delta(i,j)$
- Actual shortest paths: Predecessor matrix $\Pi = (\pi_{ij})$
  - π_{ij} = NIL if i=j or there is no path from i to j
  - π_{ij} = predecessor of j on some path from i to j otherwise

Predecessor Subgraph

- The subgraph induced by the i-th row of the matrix Π is a shortest path tree with root i
- For each vertex $i \in V$ we define the predecessor subgraph $G_{\pi,i}=(V_{\pi,i},E_{\pi,i})$:
  - $V_{\pi,i} = \{j \in V: \pi_{ij} \neq NIL \} \cup \{i\}$
  - $E_{\pi,i} = \{(\pi_{ij},j): j \in V_{\pi,i} \setminus \{i\}\}$

Printing APSPs

```
Print-APSP(Π,i,j)
  if i = j then print i
    else if π_ij = NIL
           then print no i-j path
           else Print-APSP(Π,i, π_ij )
                print j
```

Some Notation

- Graph G has $|V|=n$ vertices
- Matrix are denoted in uppercase D,W,L
- Matrix elements: d_{ij}, w_{ij}, l_{ij}
- Iterates of matrices: $D^{(m)} = (d^{(m)}_{ij})$

Shortest Paths and Matrix Multiplication

- Dynamic Programming approach:
  - Characterize the structure of an optimal solution
  - Define its value recursively
  - Compute a solution in a bottom-up fashion
  - Constructing an optimal solution

Structure of a Shortest Path

- All subpaths of a shortest paths are shortest paths
- Graph represented by adjacency matrix $W = (w_{ij})$
- Let p be a shortest path with at most m edges
- If i=j then p has no edges and weight 0
- If $i \neq j$ then $p = i \rightsquigarrow k \rightarrow j$ with $i \rightsquigarrow k$ with at most m-1 edges and $\delta(i,j) = \delta(i,k) + w_{kj}$

Recursive Solution

- $l^{(m)}_{ij}$ is the minimum weight of any path from i to j with at most m edges
- When m=0
  - $l^{(0)}_{ij} = 0$ if $i = j$
  - $l^{(0)}_{ij} = \infty$ if $i \neq j$
- When m≥1
  - $l^{(m)}_{ij} = \min(l^{(m-1)}_{ij}, \min_{1 \leq k \leq n}\{l^{(m-1)}_{ik} + w_{kj}\}) = \min_{1 \leq k \leq n}\{l^{(m-1)}_{ik} + w_{kj}\})$ (since $w_{jj}=0$ for each j)

The Shortest Path Weight

- No negative-weight cycles → shortest paths have at most n-1 edges
- A path from i to j for which $\delta(i,j) < \infty$ is simple and with $\leq$ n-1 edges or otherwise it cannot have weight $\leq \delta(i,j)$
- Actual shortest path weight:

$$\delta(i,j) = l^{(n-1)}_{ij} = l^{(n)}_{ij} = l^{(m+1)}_{ij} = \ldots$$

Computing weights bottom-up

- Input: $W = (w_{ij})$
- We compute: $L^{(1)}$, $L^{(2)}$, …, $L^{(n-1)}$ with $L^{(m)}=(l^{(m)}_{ij})$, m=1,2,…,n-1
- $L^{(n-1)}$ contains the shortest-path weights
- By definition of $L^{(m)}$ is $L^{(1)} = W$
- Basic step: Extending shortest paths edge by edge: Given $L^{(m-1)}$ and W we obtain $L^{(m)}$

Extending Shortest Paths

Extend-Shortest-Paths(L,W)
  for i = 1 to n do
    for j = 1 to n do
      $l'_{ij} = \infty$
      for k = 1 to n do
        $l'_{ij} = \min(l'_{ij}, l_{ik} + w_{kj})$
  return L'

Matrix Multiplication Analogy

- Extend-Shortest-Paths costs $O(n^3)$
- It is like multiplying n x n matrices:
- $C=A \times B \rightarrow c_{ij} = SUM_{(k=1,n)}\ a_{ik}\ b_{kj}$
- Here:
  - $l^{(m-1)} = a$
  - $w = b$
  - $l^{(m)} = c$
  - $\min = +$
  - $+ = *$
  - $\infty = 0$

Computing Shortest-Paths Weights

- We extend shortest paths edge by edge
- We compute the sequence:
  - $L^{(1)} = L^{(0)} \times W = W$
  - $L^{(2)} = L^{(1)} \times W = W^2$
  - $L^{(2)} = L^{(2)} \times W = W^3$
  - …
  - $L^{(n-1)} = L^{(n-2)} \times W = W^{n-1}$

A Slow APSP algorithm

Slow-APSP(W)

$L^{(1)} = W$

for m = 2 to n – 1 do

$L^{(m)} = \text{Extend-Shortest-Paths}(L^{(m-1)}, W)$

return $L^{(n-1)}$

- Since Extend-Shortest-Paths is $O(n^3)$ Slow-APSP(W) is $O(n^4)$

Improving the Running Time

- Goal: Compute $L^{(n-1)}$ and not the whole sequence $L^{(1)}, L^{(2)}, \ldots, L^{(n-1)}$
- Recall: $L^{(m)} = L^{(n-1)}$ for each $m \geq n - 1$
- Repeated Squaring:
  - $L^{(1)} = L^{(0)} \times W = W$
  - $L^{(2)} = W^2 = W \times W$
  - $L^{(4)} = W^4 = W^2 \times W^2$
  - …
  - $L^{(2^{\log(n-1)})} = W^{(2^{\log(n-1)})} = W^{(2^{\log(n-1)-1})} \times W^{(2^{\log(n-1)-1})} = L^{(n-1)}$

A Faster APSP Algorithm

Faster-APSP(W)
    $L^{(1)} = W$
    $m = 1$
    while $m \leq n-1$ do
        $L^{(2m)}$ = Extend-Shortest-Paths($L^{(m)}$, $L^{(m)}$)
        $m = 2m$
    return $L^{(m)}$

- Faster-APSP(W) is $O(n^3 \log n)$

The Floyd-Warshall Algorithm

- Another dynamic programming formulation for All-Pairs Shortest Path
  - The structure of a shortest path
    - Uses intermediate vertices of a shortest path
  - Recursive solution to the ASPS problem
  - Computing the shortest path weights bottom up

Structure of a Shortest Path, 1

- An intermediate vertex of a simple path $p = \langle v_1, v_2, \ldots, v_l \rangle$ is any vertex of p in $\{v_2, \ldots, v_{l-1}\}$
- Consider $G=(V,E)$ with $V=\{1,\ldots,n\}$
- Consider $K=\{1,\ldots,k\}$, for some k
- For each $i, j \in V$ consider paths with vertices only from K
- Let p be a shortest paths among them

Structure of a Shortest Path, 2

- Relationship of p and the $i \rightsquigarrow j$ shortest path with vertices from K-1={1,…,k-1}
  - k is not intermediate in p → the int. vertices of p are in K-1 → shortest path $i \rightsquigarrow j$ with vertices in K-1 has also vertices in K
  - If k is an intermediate vertex in p then:

$$p = p_1 p_2 \text{ where } p_1 = i \rightsquigarrow k \text{ and } p_2 = k \rightsquigarrow j$$

where p_1 and p_2 have int. vertices in K-1

Recursive Solution to ASPS

- Let $d^{(k)}_{ij}$ the weight of a $i \rightsquigarrow j$ shortest path with all int. vertices in K
  - $k=0 \rightarrow d^{(0)}_{ij} = w_{ij}$
  - $k \geq 1 \rightarrow \min\{d^{(k-1)}_{ij}, d^{(k-1)}_{ik} + d^{(k-1)}_{kj}\}$
- Since for any path all intermediate vertices are in V the matrix $D^{(n)}=(d^{(n)}_{ij})$ is such that $d^{(n)}_{ij}= \delta(i,j)$, for each $i, j \in V$

Computing the Shortest-Paths Weights Bottom Up

```
Floyd-Warshall(W)
  D^(0)=W
  for k = 1 to n do
    for i = 1 to n do
      for j = 1 to n do
        d^(k)_ij=min{d^(k-1)_ij, d^(k-1)_ik + d^(k-1)_kj}
  return D^(n)
```

Running Time and Space

- The running time is clearly $\Theta(n^3)$ since the min operation and the sum takes O(1) time
- Space needed is $\Theta(n^3)$: Each of the n $D^{(k)}$ needs $\Theta(n^2)$ space
- Dropping all superscript leads to a solution that works in $\Theta(n^2)$ space

C++ implementation of Floyd-Warshall

```
void FW( int n, matrix< int > &fw ) {
  matrix< int > t( n, n ) = fw;
  for( int k = 0; k < n; k++ ) {
    for( int i = 0; i < n; i++ )
      for( int j = 0; j < n; j++ )
        fw[ i ][ j ] = min( t[ i ][ j ],
                            t[ i ][ k ] + t[ k ][ j ] );
    t = fw;
  }
}
```

Assignments

- Textbook, Chapter 25, pages 620—640
- Updated information on the class web page:

  www.ece.neu.edu/courses/eceg205/2004fa