

Lecture 12

1. Turn in HW 6, Quiz 4
2. Review & Try:
Chapter 3.1 – Math & Trig functions
Chapter 3.2 – Data Analysis functions
3. New topics:
Chapter 4.1 – Matrix Operations
Chapter 4.2 – Solutions to Linear Equations
4. Next class – Read Chapter 4.
 - 20 mins - Review types of matrix multiplication
 - Rest of class - lab on solving linear equations using matrix operations
5. Monday - Quiz on Chapter 3.1 - 3.2, Chapter 4

3.2 - Data Analysis functions– see list p.61

- **max (x)** returns largest value in a row vector
if x is a matrix, returns vector with max of each column
- **max (x,y)** returns matrix with maximums after comparing matrix x and y element by element.
- **mean (x)** calculates average of a row vector
if x is a matrix, returns vector with average of each column
- **sum (x)** computes sum of elements in a vector
if x is a matrix, returns vector with sum of each column
- **sort (x)** sorts vector into ascending order
if matrix, sorts each column into ascending order

Also:

min(x) min(x,y) prod(x) median(x) cumsum(x) cumprod

3.2 – Standard deviation & histograms

- **std (x)** computes standard deviation of the values in a vector x
- **hist (x)** generates a histogram

Creating an m-file – (review)

% before starting insert diskette

cd a:

% start an m-file (1st click file → new → m-file)

% display program purpose

disp('This program will generate a plot.')

% ask user for value z

Z=input('Enter value for Z integer between 10 and 100: ')

% create two arrays

X= 0 : 0.5 : 50;

Y= 5 * X .^2;

% plot

plot(X,Y)

% save m-file .. then run it (click debug → run)

3.1 - Math & Trig functions – (review)

- **Math functions.**

- % 1. remainder or mod function

- rem(10,3) or mod(10,3)

- % 2. “nested” functions

- round (sqrt(143))

- % 3. functions with a matrix as an argument

- abs(-10:2:10)

- **Trig functions (use radians).**

- % 4. tangent of 45 degrees

- tan(45*pi/180)

- sin(45*pi/180)

- cos(45*pi/180)

3.2.1 - Vector & matrix data analysis– (review)

% Try #1. maximum and minimum

w=[0, 3, -2, 7]; x=[3, -1, 5, 7]; y=[1,3,7; 2,8,4; 6,-1,-2]

max(w)

min (x)

max (y)

min (w,x)

% Try #2. mean and median

mean(w)

mean(y)

z=1:5

median(z)

median(w)

% Try #3. cumsum & cumprod

cumsum(z)

y

cumprod(y)

3.2.1 - Vector & matrix data analysis– (review)

% Try #1 - sorting

w **% display w to remind yourself what is in w**

sort(w)

w

% note: result of sort command is in answer (not in w)

ans

% let's put result of sort in w

w=sort(w)

% Try #2 - sort a matrix

y **% display w to remind yourself what is in w**

sort (y)

% #3 - remember that arguments can include calculations

% Before you do last sort... try to predict the answer

x **% display x to remind yourself what is in x**

w **% display w to remind yourself what is in w**

2*x+w **% display 2*x+w to see the result before sorting**

sort(2*x+w)

Chapter 4.1 – Matrix Operations

Transpose: i'th row becomes i'th column. Elements (a,b) become (b,a). => If $A = m \times n$ matrix, then $A^T = n \times m$.

% Try #1 - transpose a vector

X=2 : 2 : 10

Y=X'

% Try #2 - transpose a square matrix

A=[1, 2, 3; 4, 5, 6; 7, 8, 9]

size(A)

diag(A)

B=A'

size(B) **% should get same as A 3x3**

diag(B) **% should get same as A -> 1 5 9**

% Try #3 - transpose a non-square matrix

C=[A; 10, 11, 12]

D=C'

% predict sizes and diagonals of C and D before doing them

Chapter 4.1 – Matrix Dot Product

Definition: A dot product is a scalar computed from two vectors (must be same size)

$$\rightarrow a_1b_1 + a_2b_2 + a_3b_3 + \dots a_ib_i$$

% Try dot product by hand first to predict results

X=[4, -1, 3]

Y=[-2, 5, 2]

X.*Y **% this is element by element multiplication**

sum(X.*Y) **% this is the dot product**

% or use the built in function in MATLAB

% to calculate the dot product of the two vectors

dot(X,Y)

Chapter 4.1 – Matrix Multiplication

• NOT ELEMENT BY ELEMENT MULTIPLICATION THAT WE DID IN CHAPTER 2 → $A * B$

$C = A * B$ is calculated by taking the dot products of each ROW in A with each COLUMN in B.

$C(i,j)$ = dot product of row i in A with col j in B

This is why the # columns in A (i.e., length of rows in A) must be same as the # of rows in B (i.e., length of cols in B)

So if A is (m x p) and B is (p x n), then C is (m x n):

$$C = \begin{bmatrix} C(1,1) & C(1,2) & C(1,3) & \dots & C(1,n) \\ C(2,1) & C(2,2) & C(2,3) & \dots & C(2,n) \\ C(3,1) & C(3,2) & C(3,3) & \dots & C(3,n) \\ \dots & \dots & \dots & \dots & \dots \\ C(m,1) & C(m,2) & C(m,3) & \dots & C(m,n) \end{bmatrix}$$

Chapter 4.1 – Matrix Multiplication

- When can you do it?
 - inner dimensions must be equal
- What are dimensions of results?
 - outer dimensions

OK to do:

Matrix X is:	Matrix Y is:	Result will be:
2 by 3	3 by 2	2 by 2
4 by 2	2 by 4	4 by 4
5 by 5	5 by 5	5 by 5
m by n	n by p	m by p

CAN'T DO:

4 by 3	4 by 3	Error!
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Chapter 4.1 – Matrix Multiplication

* NOT ELEMENT BY ELEMENT MULTIPLICATION

THAT WE DID IN CHAPTER 2 → $A \cdot B$

% Try this where A is (2 x 3) and B is (3 x 3)

% result of matrix multiplication is (2 x 3) matrix C

$A = [2, 5, 1; 0, 3, -1]$

$B = [1, 0, 2; -1, 4, -2; 5, 2, 1]$

% calculate each element in resulting matrix C

$C(1,1) = A(1,1) \cdot B(1,1) + A(1,2) \cdot B(2,1) + A(1,3) \cdot B(3,1)$

$C(1,2) = A(1,1) \cdot B(1,2) + A(1,2) \cdot B(2,2) + A(1,3) \cdot B(3,2)$

$C(1,3) = A(1,1) \cdot B(1,3) + A(1,2) \cdot B(2,3) + A(1,3) \cdot B(3,3)$

$C(2,1) = A(2,1) \cdot B(1,1) + A(2,2) \cdot B(2,1) + A(2,3) \cdot B(3,1)$

$C(2,2) = A(2,1) \cdot B(1,2) + A(2,2) \cdot B(2,2) + A(2,3) \cdot B(3,2)$

$C(2,3) = A(2,1) \cdot B(1,3) + A(2,2) \cdot B(2,3) + A(2,3) \cdot B(3,3)$

% easy way to do matrix multiplication in MATLAB

$D = A \cdot B$

Chapter 4.1 – Matrix Multiplication

* For Quiz, should be able to compute (by hand):

$A = \begin{bmatrix} 2 & 1 \\ 0 & -1 \\ 3 & 0 \end{bmatrix};$

$B = \begin{bmatrix} 1 & 3 \\ -1 & 5 \end{bmatrix};$

$C = \begin{bmatrix} 3 & 2 \\ -1 & -2 \\ 0 & 2 \end{bmatrix};$

$D = \begin{bmatrix} 1 & 2 \end{bmatrix}$

DB^2 (Matlab command = $D*B^2$) (What if $D*B.^2$?)

BC^T (Matlab command = $B*C'$)

$(CB)D^T$ (Matlab command = $(C*B)*D'$)

AC^T (Matlab command = $A*C'$)

Practice on your own (later) - check using Matlab.

Chapter 4.1 – Identity Matrix

* An identity matrix is composed of:

1's on the main diagonal and 0's everywhere else.

If A is a square matrix and I is an identity matrix of the same size... then $A*I = A$ also $A*I = I*A$

`% try this`

`% generate identity matrix`

`I=eye(3)`

`A=[1, 0, 2; -1, 4, -2; 5, 2, 1]`

`A*I`

`I*A`

`% note that the answer to A*I is the same as I*A`

`(A*I)-(I*A)`

Chapter 4.1 – Matrix Inverse

* If A is a square matrix ...

.....then the inverse of A is A^{-1} ...

Definition: $A * A^{-1} = I$ (identity matrix)

.... also $A * A^{-1} = A^{-1} * A$

MATLAB COMMAND IS: `inv(A)`

% try creating a matrix inverse

`A=[2, 1; 4, 3]`

`A_inverse=inv(A)`

`A*A_inverse`

`A_inverse*A`

% note: answer to both of the above is identity matrix

Chapter 4.2 – Solutions to Linear Equations

* Let's solve the following system of equations:

$$3x_1 + 5x_2 = -7$$

$$2x_1 - 4x_2 = 10$$

Linear Algebra Format:

* Put the coefficients on left side into matrix A

* Put the numbers on the right side into column B

* Unknowns are column X

$$A = \begin{pmatrix} 3 & 5 \\ 2 & -4 \end{pmatrix}$$

$$X = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$$

$$B = \begin{pmatrix} -7 \\ 10 \end{pmatrix}$$

$AX = B$ (to solve for X → multiply both sides by the inverse of A) so $X = \text{inv}(A) * B$

Chapter 4.2 – Solutions to Linear Equations

```
% Try solving it in MATLAB
% put coefficients from left side of the equations into A
A=[3  5;  2  -4]
% put coefficients from right side of equations into
%      column vector B
B=[-7; 10]
% find solutions (X) by multiplying the inverse of A by B
X=inv(A)*B
```

```
% Another way to solve Linear Equations
% ..... using Matrix Left Division
% uses Gaussian elimination without forming the inverse
A \ B
% this is a direct method => quicker and more precise
```

Chapter 4 – Summary

Two methods for solving a system of equations that are in the format: $A * X = B$

1. using inverse:

$$X = \text{inv}(A) * B$$

2. using matrix left divisions:

$$X = A \setminus B$$

Rules for doing matrix multiplication:

1. “inner dimensions” of matrices must be equal

2. resulting matrix will equal “outer dimensions”

Chapter 4.1 – Matrix Determinant

* If A is a square 2 by 2 matrix = $[a_{11} \ a_{12}; \ a_{21} \ a_{22}]$
.....then the determinant of A is a scalar

$$|A| = (a_{11} * a_{22}) - (a_{21} * a_{12})$$

MATLAB COMMAND IS: det(A)

% try calculating the determinant of a 2 by 2 matrix

% first do it by hand to predict results

A=[1, 3; -1, 5]

det(A)

% try determinant of a 3 by 3 matrix – see page 92

B=[1 3 0; -1 5 2; 1 2 1]

det(B)

% try determinant of singular matrix (doesn't have inverse)

C=[2, 4; -1, -2]

det(C)

inv(C)